



# Analysing the Result Involution Graph of the Group J<sub>3</sub>

Ahmed Arkan Meteab<sup>1</sup> and Ali Abd Aubad<sup>2,\*</sup>

<sup>1,2</sup>Department of Mathematics, College of Science, University of Baghdad, Baghdad, Iraq. \*Corresponding Author.

Received: 12 April 2023	Accepted: 18 May 2023	Published: 20 October 2024
doi.org/10.30526/37.4.3405		

### Abstract

Assume that G be a finite group and let I(G) be the set of the involution elements in G. The result involution graph denoted by ,  $\Gamma_G^{RI}$ , is an undirected simple graph having the elements of G as a vertex set. Moreover, two vertices in  $\Gamma_G^{RI}$  are connected by an edge if they are distinct and their product belong to I(G). The objective of this work is to investigate the result involution graph for the Janko group J<sub>3</sub>. In this paper we compute different result involution graph features, such as the radius, the diameter, the clique number, and the girth. Furthermore, the connectedness of the result involution graph is determined. All of the steps needed for analyzing the result involution graph were carried out using the computational technique along with theoretical support.

Keywords: Janko Groups, Result Involution Graph, Connectedness, Girth.

### 1. Introduction

One of the most important techniques for examining group structure is possibly the action of a group on a graph. The numerous and diverse graphs that have been analyzed for various groups are highlighted by the substantial citations in [1-14]. If an element of a group has order 2, it is said to be involution. Involutions of groups significantly affect the way it is structured. For instance, the categorization of finite simple groups heavily depends on the study of involutions. An S3-involution graph for a group G was first introduced by Devillers and Giudici in [15] as a graph with a G-classes of involution as a vertex set, where two vertices are adjacent if they generate an S<sub>3</sub>-subgroup in a certain G-class. They looked at the structure of S<sub>3</sub>-involution graph and general characteristics for the group PSL (2,q) when q is greater than 3. Define I(G) as a set of the involution elements in a finite group G. The result involution graph is known as the simple undirected graph with vertex set being the elements of G with two vertices x, y G are adjacent if  $x \neq y$  and  $xy \in I(G)$ , and is denoted by  $\Gamma_G^{RI}$ . Jund and Salih reported the result involution graph and its attributes for the first time in [16]. In their analysis, they demonstrated that the graphs  $\Gamma_{Sn}^{RI}$  and  $\Gamma_{An}^{RI}$  are connected graphs for n>4 and have a maximum diameter, radius, and girth of 3 and 3. Also, they provide some really helpful qualities for the result involution graphs of the quaternion group and the dihedral group. Nevertheless, Aubad and Salih looked at the structure of the

401

<sup>© 2024</sup> The Author(s). Published by College of Education for Pure Science (Ibn Al-Haitham), University of Baghdad. This is an open-access article distributed under the terms of the <u>Creative Commons</u> <u>Attribution 4.0 International License</u>

involution graphs that were produced for the whole list of the Mathieu sporadic simple groups as mentioned in [17]. Furthermore, the result involution graphs for the Conway group  $Co_3$  are analyzed with full information in [18].

Examining the result involution graph for the Janko group  $J_3$ , is the aim of this article. Together with the connectedness of the result involution graph, we show many graph properties including the radius, diameter, clique number, and girth. The paper is set up like follows: We offer some observations and graph notations for the result involution graph in section 2. A number of results about  $\Gamma_{J3}^{RI}$  are provided in section 3. We draw our concluding conclusions and make suggestions for more study in section 4.

# 2. Preliminary

We begin the section by defining a few concepts and outlining several facts that will be important to the thesis later on. First let G be a finite group moving forward. Let  $sI_G=|I(G)|$  be the size of the set I(G), where I(G) be the set of the involution elements in G as mentioned in the introduction. We begin with the following formula to determine how many edges there are in the result involution graph:

**Proposition 2.1 [17]:** Let G be a finite group, and let F represent the number of elements of order 4 in G. Then the number of edges in the result involution graph is calculated using the following formula  $\frac{1}{2} (\mathbf{sI}_G |G| - F)$ .

We should notice that if G is a finite group with large number of elements, then the  $\Gamma_G^{RI}$  has a huge vertex set. The result involution graph of G is then exceedingly difficult to handle. To resolve this issue, we use the resize graph idea, which define as follows:

**Definition 2.2 [17]:** Assume that G be a finite group, the resize graph of G,  $\Gamma_G^{RS}$ , has a vertex set the whole G-conjugacy classes with two vertices (G-conjugacy classes) X, Y  $\subseteq$  G, are adjacent if X $\neq$ Y and there are  $v_1 \in$ X and  $v_2 \in$  Y such that  $v_1$ ,  $v_2$  are adjacent vertices in  $\Gamma_G^{RI}$ . The following results displays a relationship between a result involution graph and a resize graph:

**Proposition 2.3** [17]: Let G be a finite group. Then the connectivity of the graphs  $\Gamma_G^{RI}$  and  $\Gamma_G^{RS}$  are isomorphic graphs.

These findings will be illustrated by the example that follows. We will mostly employ GAP [19] and YAGS [20] as a computational approach in the following example.

**Example 2.4:** Let G be an alternating group of degree 4. Then the result involution graph  $\Gamma_{A4}^{RI}$  contains the following vertices: {*e*,(2,3,4), (2,4,3), (1,2)(3,4), (1,2,3), (1,2,4), (1,3,2), (1,3,4), (1,3)(2,4), (1,4,2), (1,4,3), (1,4)(2,3)}. Then we can conclude the figure below that the graph  $\Gamma_{A4}^{RI}$  is disconnected with two components. One of these components has four vertices labels by the numbers {1,9,4,12} and the subgraph induced with this vertex is the compete graph *K*<sub>4</sub>. On the other hand, the subgraph induced by the vertices labels by {2,3,5,6,7,8,10,11}. This graph is 3-regular graph with dimeter and radius of size 3. Moreover, clique number of size 2 and girth 4. This information can be seen the following **Figure**:



**Figure 1.** The Structure of the Result Involution Graph  $\Gamma_G^{RI}$ , G $\cong$ A<sub>4</sub>.

On the other hand, the resize graph of G,  $\Gamma_{A4}^{RS}$  has vertex set present as {1A,2A,3A,3B}. In the next figure we can see that resize graph of A<sub>4</sub> is (1,1)-biregular disconnected graph has vertex set can be split into two disjoint vertices can be labeled by X={1,2} and Y={3,4}:



**Figure 2.** The Structure of the Resize Graph  $\Gamma_G^{RS}$ , G $\cong$ A<sub>4</sub>.

### 3. Results

In this section we will look at the structure of the result involution graph for the Janko group J<sub>3</sub>. To achieve the goal of the study, we will use GAP and the Online Atlas [21]. We should note that the group J<sub>3</sub> has only one class of involution namely 2A with size equal to 26163. There are several involutions to take into account as a consequence. Hence, in order to arrive at our observations, we will investigate the resizing graph  $\Gamma_{J3}^{RS}$ .

## 3.1 The Structures of $\Gamma_{I3}^{RS}$

The Online Atlas reveals that  $J_3$  has different 21 conjugacy classes. Therefore, the resizing graph  $\Gamma_{J3}^{RS}$  has order 42. Furthermore, the vertex set of  $\Gamma_{J3}^{RS}$  could now be stated in the following manner: {1A, 2A, 3A, 3B, 4A, 5A, 5B, 6A, 8A, 9A, 9B, 9C, 10A, 10B, 12A, 15A, 15B, 17A, 17B, 19A, 19B}.

In addition, the vertex degree sequence is shown below:

 $\{1, 18, 14, 17, 18, 19, 19, 18, 19, 18, 18, 18, 19, 19, 19, 19, 19, 19, 19, 19, 18, 18\}$ 



**Figure 3.** The Structure of the Resize Graph  $\Gamma_G^{RS}$ , G $\cong$ J<sub>3</sub>. According to the data in **Figure 3**,  $\Gamma_{J3}^{RS}$  is connected and has the following characteristics:

**Table 1.** Properties of the Resize Graph  $\Gamma_{I3}^{RS}$ .

$\Gamma_G^{RS}$	$E(\Gamma_G^{RS})$	Girth	Clique Number	Radius	Diameter
G≅J <sub>3</sub>	183	3	17	2	3

### **3.2 The Edges Set of Result Involution Graphs**

In this section, we provide comprehensive information about the edges set of the result involution graph  $\Gamma_{J3}^{RI}$  for the Janko group J<sub>3</sub>. The data concern the number of edges connecting any two G-Conjugacy elements. The findings will be crucial in assessing the construct of the result involution graph of J<sub>3</sub>. We will use GAP and the Online Atlas to get the intended result. We should be informed of that, in the elements of the class 5A there are an edges with the remaining J<sub>3</sub>-conjugacy classes except the identity element. This can be seen in the following set:

 $\{2A(33488640), 3A(25116480), 3B(167443200), 4A(418608000), 5A(598609440), 5B(1573966080), 6A(1783270080), 8A(5425159680), 9A(1557221760), 9B(1557221760), 9C(1557221760), 10A(4651572096), 10B(4470733440), 12A(3717239040), 15A(3265142400), 15B(2662346880), 17A(2561880960), 17B(2561880960), 19A(2310716160), 19B(2310716160)) \}.$ 

In addition, we can find 26163 edges between the elements of the class 2A.

## **3.3 The Structures of** $\Gamma_{I3}^{RI}$

For the Janko group  $J_3$ , the structures of the result involution graph are fully described in the following theorem:

**Theorem 3.1:** The result involution graph for the Janko group  $J_3$  is connected with diameter 3, radius 2, and girth 3.

**Proof:** The resizing graph of  $J_3$  is connected using **Table 1**. As a result, by utilizing **Proposition 2.3**, we are able to determine how  $\Gamma_{J_3}^{RI}$  is connected. In addition, between the elements of the class 2A there are 26163 edges and these elements adjacent with the identity element of  $J_3$ . Hence, we have a cycle with a length of 3 in the graph  $\Gamma_{J_3}^{RI}$ . Therefore, the result involution graph has girth 3 in this case. Furthermore, The class 5A vertices and the identity element are not adjacent. But, during the classes 2A, these vertices were connected to the identity. As a result, in this scenario, the radius is 2. Moreover, the diameter is 3 due to the other vertices maximum distance being 3.

We provide the following significant corollaries in light of the preceding finding:

**Corollary 3.2:** Suppose that G be the Janko groups J<sub>3</sub>. Then for any distinct elements  $x, y \in$  G, one of the following are holds:

- i- Their product is an involution element.
- ii- There exist an certain  $z \in G$ , satisfy its product with x and y produce an involution elements.
- iii- There are an elements  $z, w \in G$ , satisfy (xz), (zw) and (wy) are involution elements.
- iv-  $J_3$  has three distinct components, any one of them has an involution product with the others.

**Proof:** By applying the outcomes of **Theorem 3.1** we have the diameter 2 and the radius 2 for the result involution graph of G. Therefore, when x and y have distance one then their product is an involution element so (i) is hold. If the distance between x and y equal 2, then one can find z in G satisfying (ii). Finally, to prove (iii) the distance between x and y equal to 3, implies there are such  $z, w \in G$  satisfy the conditions of (iii). Finally, the result involution graph of G with girth 3. As a result, the characterization of the result involution graph normally leads to the proof of iv.

### 4. Conclusion

This study analyses the result involution graph for the Janko group  $J_3$ . the computational method used to determine certain graph properties. Detailed information about the resize graph, for example, as well as the radius, diameter and circumference. The results of this study can be applied to the study of more complicated simple groups, including monster groups, pariah groups and Lie-type exceptional groups.

### Acknowledgment

The authors would like to thank the University of Baghdad (https://uobaghdad.edu.iq/), Department of Mathematics in the College of Sciences for their motivation and support.

### **Conflict of Interest**

The authors declare that they have no conflicts of interest.

#### Funding

No funding.

#### References

 Aubad, A.; Rowley, P. Commuting Involution Graphs for Certain Exceptional Groups of Lie Type. Graphs and Combinatorics 2021, 37,1345–1355. <u>https://doi.org/10.1007/s00373-021-02321-w.</u>

- 2. Bhat,V.K; Sharma, K. On Some Topological Indices for the Orbit Graph of Dihedral Groups. *Journal* of Combinatorial Mathematics and Combinatorial Computing **2023**, *117*, 195-208. https://doi.org/10.61091/jcmcc117-18.
- 3. Cameron, P. J.; Kuzma, B. Between the enhanced power graph and the commuting graph. *Journal of Graph Theory*, **2023**, *102*(2), 295-303. <u>https://doi.org/10.1002/jgt.22871.</u>
- Gaftan, A.M.; Mohammed, A.S.; Subhi.O.H. Cryptography by Using"Hosoya"Polynomials for"Graphs Groups of Integer Modulen and"Dihedral Groups with'Immersion"Property. *Ibn AL-Haitham Journal For Pure and Applied Sciences*, 2018, 31,151–159. https://doi.org/10.30526/31.3.2008.
- 5. Hamdi, H. Investigation the order elements 3 in certain twisted groups of lie type. *Italian Journal of Pure and Applied Mathematics*, **2022**, 48, 621-629. https://ijpam.uniud.it/onlineissue/202248/48%20Hamdi.pdf.
- Khudhur, P.M.; Haji, R.R.; Khasraw, S.M. The Intersection Graph of Subgroups of the Dihedral Group of Order 2pq. *Iraqi Journal of Sciences*, 2021, 62, 4923–4929. <u>https://doi.org/10.24996/ijs.2021.62.12.30.</u>
- 7. Konstantinova, E.V.; Kravchuk, A. Spectrum of the Transposition graph. *Linear Algebra and its Applications*, **2022**, *654*, 379 389. <u>https://doi.org/10.1016/j.laa.2022.08.033</u>.
- 8. Kumari, M.L.; Pandiselvi, L.; Palani, K. Quotient Energy of Zero Divisor Graphs And Identity Graphs. *Baghdad Sci.J*, **2023**, *20*, 0277. <u>https://doi.org/10.21123/bsj.2023.8408.</u>
- 9. Nawaf, A. J.; Mohammad, A. S. Some Topological and Polynomial Indices (Hosoya and Schultz) for the Intersection Graph of the Subgroup of〖 Z〗\_\_(r^n). ). *Ibn AL-Haitham Journal For Pure and Applied Sciences*, **2021**, *34*, 68-77. <u>https://doi.org/10.30526/34.4.2704.</u>
- Neamah, A. A.; Majeed, A. H.; Erfanian, A. The generalized Cayley graph of complete graph K<sub>n</sub> and complete multipartite graphs K <sub>(n,n)</sub> and K<sub>(n,n,n)</sub>. *Iraqi Journal of Science*, **2022**, *63*(7), 3103–3110. <u>https://doi.org/10.24996/ijs.2022.63.7.31</u>.
- 11. Newman, A. Abelian Groups from Random Hypergraphs. *Combinatorics Probability Computing*, *Cambridge University Press*, **2023**, *32*, 654–664. <u>https://doi.org/10.1017/s0963548323000056</u>.
- Romdhini, M. U.; Nawawi, A.; Chen, C. Y. Neighbors degree sum energy of commuting and noncommuting graphs for dihedral groups. *Malaysian Journal of Mathematical Sciences*, 2023, 17(1), 53–65. <u>https://doi.org/10.47836/mjms.17.1.05.</u>
- Roslly, S. R. D.; Ab Halem, N. F. A. Z.; Zailani, N. S. S.; Alimon, N. I.; Mohammad, S. A. Generalization of Randic<sup>'</sup> Index of the Non-commuting Graph for Some Finite Groups. *Malaysian Journal of Fundamental and Applied Sciences*, 2023, 19(5), 762-768. https://doi.org/10.11113/mjfas.v19n5.3047.
- 14. Tolue, B. The twin non-commuting graph of a group. *Rendiconti del Circolo Matematico di Palermo Series 2* **2020**, *69*(2), 591–599 . <u>https://doi.org/10.1007/s12215-019-00421-4</u>.
- 15. Devillers, A.; Giudici, M. Involution graphs where the product of two adjacent vertices has order three. *Journal of the Australian Mathematical Society* **2008**, *85*, 305–322. doi:10.1017/S1446788708000839.
- 16. Jund, A.; Salih, H. Result involution graphs of finite groups. *Journal of Zankoy Sulaimani*, **2021**, 23, 113–118. <u>doi:10.17656/jzs.10846</u>.
- 17. Aubad, A.; Salih, H. More on Result Involution Graphs. *Iraqi Journal of Science* **2023**, *64*, 331–240. <u>https://doi.org/10.24996/ijs.2023.64.1.30.</u>
- Oudah, M.M.; Aubad, A. Computational Investigation of The Result Involution Graphs for The Conway Group Co3. *Wasit Journal of Pure Sciences* 2023, 2, 141–146. <u>https://doi.org/10.31185/wjps.112.</u>
- 19. The GAP Group. GAP Groups, Algorithms, and Programming. Version 4.12.2. Available online: <u>http://www.gap-system.org/</u> (accessed on 10 January 2023).
- 20. Cedillo, J.; MacKinney-Romero.R.; Pizaa.M.A.; Robles.I.A.; Yet Another Graph System, YAG, "

Version 0.0.5. Available online: <u>http://brauer.maths. qmul.ac.uk /Atlas /v3/ (</u>accessed on 1 February 2023).

 Wilson, R. A.; Walsh .P.; Tripp.J.; Suleiman.I.; Parker .R.; Norton.S.; Nickerson S. J.; Linton.S.; Bray J. N.; A world wide web Atlas of Group Representations. Version 3 Available online: http://brauer.maths.qmul.ac.uk/Atlas/v3/ (accessed on 30 October 2022).