(σ,τ) - Strongly Derivations Pairs on Rings

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Abstract

Let R be an associative ring. In this paper we present the definition of (σ,τ) - Strongly derivation pair and Jordan (σ,τ) - strongly derivation pair on a ring R, and study the relation between them. Also, we study prime rings, semiprime rings, and rings that have commutator left nonzero divisior with (σ,τ) - strongly derivation pair, to obtain a (σ,τ) - derivation. Where σ,τ : R \rightarrow R are two mappings of R.

Keywords

Prime ring, semiprime ring, (σ,τ) -derivation, (σ,τ) -Strongly derivation pair, Jordan (σ,τ) -Strongly derivation pair.

§1 Basic Concepts

Deinition 1.1: [1]

A nonempty set R is said to be associative ring if in R there are defined two operations, denoted by + and . respectively, such that for all a, b, c in R:

- 1- a + b is in R
- 2- a + b = b + a
- 3- (a+b) + c = a + (b+c)
- 4- There is an element 0 in R such that a+0 = a (for every a in R)
- 5- There exists an element -a in R such that a + (-a)=0.
- 6- a.b is in R.
- 7- a. (b.c) = (a.b).c
- 8- a. (b+c) = a.b + a.c and (b+c).a = b.a + c.a

Deinition 1.2: [1]

A ring R is called prime ring if for any a, $b \in R$, a R b = {0}, implies that either a=0 or b=0.

Definition 1.3:[1]

A ring R is called semiprime ring if for any $a \in R$, $aRa = \{0\}$, implies that a=0.

Remark 1.4:[1]

Every prime ring is semiprime ring, but the converse in general is not true. The following example justifies this remark.

Example 1.5: [1]

 $R = Z_6$ is a semiprime ring but is not prime. Let $a \in R$ such that $aRa = \{0\}$, implies that $a^2 = 0$, hence a=0, therefore R is a semiprime ring. But R is not prime, since $2 \neq 0$ and $3 \neq 0$ implies that $2R3 = \{0\}$. **Definition 1.6:[2]**

A ring R is said to be n-torsion free, where $n\neq 0$ is an integer if whenever n a=0, with a \in R, then a=0.

Definition 1.7:[2]

Let R be a ring. A Lie product[,] on R is defined as [x,y]=xy - yx, for all $x,y \in R$.

Definition 1.8:[2]

Let R be a ring. An additive mapping d:R \rightarrow R is called a derivation if d(xy)= d(x)y + xd(y), for all x,y \in R and we say that d is a Jordan derivation if d(x²)=d(x)x+xd(x), for all x \in R.

Definition 1.9:[3]

Let R be a ring. An additive mapping d:R \rightarrow R is called a (σ,τ)-derivation, where σ,τ : R \rightarrow R are two mappings of R, if d(xy)= d(x)\sigma(y) + $\tau(x)$ d(y), for all x,y \in R, and we say that d is a Jordan (σ,τ)-derivation if d(x²)=d(x) $\sigma(x)+\tau(x)$ d(x), for all $x \in$ R.

Definition 1.10:[4]

Let R be a ring, additive mappings $d,g : R \rightarrow R$ is called S-derivation pair (d,g) if satisfies the following equations:

$$\begin{split} &d(xy) = d(x)y + xg(y), \text{ for all } x, y \in R. \\ &g(xy) = g(x)y + xd(y), \text{ for all } x, y \in R. \\ &\text{And is called Jordan S-derivation pair if:} \\ &d(x^2) = d(x)x + xg(x), \text{ for all } x \in R. \\ &g(x^2) = g(x)x + xd(x), \text{ for all } x \in R. \end{split}$$

Example 1.11:[4]

Let R be a non commutative ring and let $a, b \in R$, such that xa=xb=0, for all $x \in R$. Define d, g : R \rightarrow R, as follows: d(x) = ax, g(x) = bxThen (d,g) is a S-derivation pair of R.

Remark 1.12:[4]

Every S-derivation pair is a Jordan S-derivation pair, but the converse is in general not true. The following example illustrates this remark.

Example 1.13:[4]

Let R be a 2-torsion free non commutative ring, and let $a \in R$, such that xax = 0, for all $x \in R$, but $xay \neq 0$, for some $(x \neq y) \in R$. An additive pair d,g : $R \rightarrow R$ is defined as d(x) = xa + ax, g(x) = [x,a]Then (d,g) is Jordan S-derivation pair, but not a S-derivation pair.

Definition 1.14:[5]

A ring R is said to be a commutator right (resp. left) nonzero divisior, if there exists elements a and b of R, such that c[a,b] = 0 (resp. [a,b]c = 0) implies c=0, for every $c \in R$.

$\S_2(\sigma,\tau)$ -S-Derivation pairs

In this section, we will introduce the definition of (σ,τ) -Strongly derivation pair, and we denoted by (σ,τ) -S-derivation pair, and Jordan (σ,τ) -Strongly derivation pair and we denoted by Jordan (σ,τ) -S-derivation pair, also we will give the relation between them. Where $\sigma,\tau : R \to R$ are two mappings on R. Now, in this section we introduce the principle definition.

Definition 2.1

Let R be a ring, additive mappings d,g : R \rightarrow R is called (σ , τ)-S-derivation pair (d,g) where σ , τ : R \rightarrow R are two mappings of R, if satisfy the following equations: d(xy)=d(x)\sigma(y) + τ (x)g(y), for all x,y \in R. g(xy)=g(x)\sigma(y) + τ (x)d(y), for all x,y \in R. And is called Jordan (σ , τ)-S-derivation pair if: d(x²)=d(x)\sigma(x) + τ (x)g(x), for all x \in R. g(x²)=g(x)\sigma(x) + τ (x)d(x), for all x \in R. The following example explains the principle definition:

Example 2.2

Let R be a non commutative ring and let $a, b \in R$, such that $\tau(x) a = \tau(x)b = 0$, for all $x \in R$. Define d, g: $R \to R$ as follows: $d(x) = a \sigma(x), g(x) = b \sigma(x)$, for all $x \in R$ where $\sigma, \tau: R \to R$ are two endomorphism mappings. Then (d,g) is a (σ,τ) -S-derivation pair of R. Let $x, y \in R$, so: $d(xy) = a\sigma(xy)$ $= a\sigma(x)\sigma(y) + \tau(x) b\sigma(y)$ $= d(x)\sigma(y) + \tau(x)g(y)$ Also: $g(xy) = b\sigma(xy)$ $= b\sigma(x)\sigma(y)$ $= b\sigma(x)\sigma(y) + \tau(x) a\sigma(y)$ $= g(x)\sigma(y) + \tau(x)d(y)$ Hence (d,g) is a (σ,τ)-S-derivation pair.

Remark 2.3

Every (σ,τ) -S-derivation pair is a Jordan (σ,τ) -S-derivation pair, but the Converse is in general not true.

The following example illustrates this:

Example 2.4

Let R be a 2-torsion free non commutative ring, and let $a \in R$, such that $\tau(x) a \sigma(x) = 0$, for all $x \in R$, but $\tau(x) a \sigma(y) \neq 0$, for some $(x \neq y) \in R$. Define an additive pair d,g: $R \rightarrow R$, as follows:

 $d(x) = \tau(x) a + a \sigma(x), g(x) = \tau(x)a - a\sigma(x), \text{ for all } x \in R.$ where $\sigma,\tau: R \to R$ are two endomorphism mappings. Then (d,g) is a Jordan (σ,τ) -S-derivation pair, but not a (σ,τ) -S-derivation pair. Let $x, y \in R$, so: $d(x^2) = \tau(x^2) a + a\sigma(x^2)$ $d(x)\sigma(x) + \tau(x)g(x) = (\tau(x)a + a\sigma(x)) \sigma(x) + \tau(x)(\tau(x)a - a\sigma(x))$ $=\tau(x)a\sigma(x) + a\sigma(x)\sigma(x) + \tau(x)\tau(x)a - \tau(x)a\sigma(x)$ $=\tau(x^2)a + a\sigma(x^2)$ Hence $d(x^2) = d(x)\sigma(x) + \tau(x) g(x)$ Also: $g(x^2) = \tau(x^2)a - a\sigma(x^2) = g(x)\sigma(x) + \tau(x)d(x)$ Thus, (d,g) is Jordan (σ,τ) -S-derivation pair. Now, we show that (d,g) is not (σ,τ) -S-derivation pair. $d(xy) = \tau(xy)a + a\sigma(xy)$ $d(x)\sigma(y) + \tau(x)g(y) = (\tau(x)a + a\sigma(x)) \sigma(y) + \tau(x)(\tau(y)a - a\sigma(y))$ $=\tau(x)a\sigma(y) + a\sigma(x)\sigma(y) + \tau(x)\tau(y)a - \tau(x)a\sigma(y)$ $=\tau(xy)a + a\sigma(xy)$ Hence $d(xy)=d(x) \sigma(y) + \tau(x)g(y)$ But: $g(xy) = g(x)\sigma(y) + \tau(x)d(y)$ $=(\tau(x)a - a\sigma(x))\sigma(y) + \tau(x)(\tau(y)a + a\sigma(y))$ $=\tau(x)a\sigma(y) - a\sigma(x)\sigma(y) + \tau(x)\tau(y)a + \tau(x)a\sigma(y)$ $=\tau(xy)a - a\sigma(xy) + 2\tau(x)a\sigma(y)$ On the other hand: $g(xy) = \tau(xy)a - a\sigma(xy)$ Since $\tau(x)a\sigma(y)\neq 0$, for some $x\neq y \in \mathbb{R}$, the two expressions are not equal, hence we get (d,g) is not (σ, τ) -S-derivation pair.

Proposition 2.5

Let R be a semiprime ring. Suppose that σ,τ are automorphisms of R. If R admits a (σ,τ) -S-derivation pair (d,g), such that d(x) g(y)=0(resp. g(x) d(y)=0), for all $x,y \in R$, then d=0 (resp. g=0).

Proof

We have d(x)g(y)=0, for all $x, y \in R$ (1) Replacing yx for y in (1) and using (1), we have: d(x)g(yx)=0, for all $x,y \in R$. $d(x)(g(y)\sigma(x) + \tau(y)d(x))=0$, for all $x, y \in R$. $d(x)g(y)\sigma(x) + d(x)\tau(y)d(x)=0$, for all $x, y \in \mathbb{R}$. $d(x)\tau(y)d(x)=0$, for all $x, y \in \mathbb{R}$. (2) By semiprimeness of $R_{1}(2)$ gives: d(x)=0, for all $x \in R$. If we have g(x)d(y)=0, for all $x, y \in \mathbb{R}$ (3) Replacing yx for y in (3) and using (3), we have: g(x)d(yx)=0, for all $x,y \in R$. $g(x)(d(y)\sigma(x) + \tau(y)g(x))=0$, for all $x, y \in \mathbb{R}$. $g(x)d(y)\sigma(x) + g(x)\tau(y)g(x)=0$, for all $x,y \in R$. $g(x)\tau(y)g(x)=0$, for all $x, y \in \mathbb{R}$ (4) By semiprimeness of R, (4) gives: g(x)=0, for all $x \in R$.

Proposition 2.6

Let R be a semiprime ring. Suppose that σ,τ are automorphisms of R. If R admits a (σ,τ) -S-derivation pair (d,g), such that $d(x) = \pm \sigma(x)$ (resp. $g(x) = \pm \sigma(x)$), for all $x \in R$, then g=0 (resp. d=0).

Proof

We have $\begin{aligned} d(x) = \sigma(x), \text{ for all } x \in R _ (1) \\ \text{Replacing } x \text{ by } xy \text{ in } (1) \text{ and using } (1), \text{ we get:} \\ d(xy) = \sigma(xy), \text{ for all } x, y \in R. \\ d(x)\sigma(y) + \tau(x)g(y) = \sigma(xy), \text{ for all } x, y \in R. \\ \sigma(x)\sigma(y) + \tau(x)g(y) = \sigma(x)\sigma(y), \text{ for all } x, y \in R. \\ \tau(x)g(y) = 0, \text{ for all } x, y \in R _ (2) \\ \text{Left multiplication of } (2) \text{ by } g(y), \text{ leads to:} \\ g(y)\tau(x)g(y) = 0, \text{ for all } x, y \in R _ (3) \\ \text{By semiprimeness of } R, (3) \text{ gives:} \\ g(y) = 0, \text{ for all } y \in R. \end{aligned}$ Similarly, we can show if $d(x)=-\sigma(x)$, for all $x \in R$, then g=0In the same way, if $g(x)=\pm \sigma(x)$, for all $x \in R$, then d=0.

Proposition 2.7

Let R be any ring and σ , τ are two mappings on R. Then

- 1- If (d,g) is a (σ,τ) -S-derivation pair on R, then d+g is a (σ,τ) -derivation.
- 2- If (d,g) is a Jordan (σ , τ)-S-derivation pair on R, then d+g is a Jordan (σ , τ)-derivation.

Proof

1- We have (d,g) is a (σ,τ) -S-derivation pair, so $d(xy) = d(x) \sigma(y) + \tau(x)g(y)$, for all $x,y \in \mathbb{R}$ (1) $g(xy) = g(x) \sigma(y) + \tau(x)d(y)$, for all $x,y \in \mathbb{R}$ (2)

By adding (1) and (2), we get

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(d+g)(xy)=(d+g)(x)\sigma(y)+\tau(x)(d+g)(y)
Hence d+g is a (\sigma,\tau)-derivation
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2- We have (d,g) is a Jordan (σ,τ) -S-derivation pair, so $d(x^2)=d(x)\sigma(x) + \tau(x)g(x)$, for all $x \in \mathbb{R}$ (3) $g(x^2)=g(x)\sigma(x) + \tau(x)d(x)$, for all $x \in \mathbb{R}$ (4) By adding (3) and (2), we get $(d+g)(x^2)=(d+g)(x)\sigma(x) + \tau(x)(d+g)(x)$, for all $x \in \mathbb{R}$.

Hence d+g is a Jordan (σ,τ) -derivation.

\S_3 Relation Between (σ, τ) -S-Derivation pairs and (σ, τ) -Derivations

In this section, we study prime rings, semiprime rings, and rings that have a commutator left nonzero divisor with (σ,τ) -S-derivation pair, to obtain a (σ,τ) -derivation.

Theorem 3.1

Let R be a 2-torsion free semiprime ring, and (d,g) be a (σ,τ) -S-derivation pair on R, then d and g are (σ,τ) -derivations. Where σ,τ are automorphisms of R.

Proof

Suppose that (d,g) is (σ,τ) -S-derivation pair. Then: $d(xyx)=d(x(yx)) = d(x)\sigma(yx) + \tau(x)g(yx), \text{ for all } x,y \in R ____(1)$ That is: $d(xyx)=d(x)\sigma(yx) + \tau(x)g(y)\sigma(x) + \tau(x)\tau(y)d(x), \text{ for all } x,y \in R ____(2)$ Also: d(xy x)=d((xy)x)=d(xy)\sigma(x) + $\tau(xy)g(x)$, for all x,y $\in R$ ____(3) That is: d(xyx)=d(x)\sigma(y)\sigma(x) + $\tau(x)g(y)\sigma(x) + \tau(xy)g(x)$, for all x,y $\in R$ ____(4) From (2) and (4), we get: $\tau(xy)(d(x)-g(x))=0$, for all x,y $\in R$ ____(5) Replace $\tau(y)$ by (d(x)-g(x)) $\tau(y) \tau(x)$ in (5), we get: $\tau(x)(d(x)-g(x))\tau(y)\tau(x)(d(x)-g(x))=0$, for all x,y $\in R$ ____(6) Since R is semiprime, we get: $\tau(x)d(x)=\tau(x)g(x)$, for all $x \in R$ ____(7) It follows that: $d(x^2)=d(x)\sigma(x)+\tau(x)d(x)$, for all $x \in R$ ____(8) And: $g(x^2)=g(x)\sigma(x)+\tau(x)g(x)$, for all $x \in R$ ____(9) Thus, by using [3, Theorem 2.3.7], we obtain that d and g are (σ, τ)-derivations on R.

Theorem 3.2

Let R be a prime, and (d,g) be a (σ,τ) -S-derivation pair on R, then d and g are (σ,τ) -derivations. Where σ,τ are automorphisms of R.

Proof

Since (d,g) is (σ,τ) -S-derivation pair, we have (see how relation (5) was obtained from relation (1) in the proof of Theorem 3.1)

 $\tau(xy)(d(x)-g(x)=0, \text{ for all } x,y \in R_{(1)}$ And, by primeness of R, we get: d(x)=g(x), for all $x \in R_{(2)}$ And hence d and g are (σ,τ) -derivations on R.

Theorem 3.3

Let R be a ring which has a commutator left nonzero divisor and (d,g) be a (σ,τ) -S-derivation pair on R, then d and g are (σ,τ) -derivations. Where σ,τ are automorphisms of R.

Proof

- 1. That is We have:
- 2. $d(yx^2)=d(y)\sigma(x^2) + \tau(y)g(x^2)$, for all x, $y \in R_{---}(1)$
- 3. That is:
- 4. $d(yx^2)=d(y)\sigma(x^2)+\tau(y)g(x)\sigma(x)+\tau(y)\tau(x)d(x)$, for all $x,y \in R_{(2)}$
- 5. On the other hand:
- 6. $d(yx^2) = d(yx)\sigma(x) + \tau(yx)g(x), \text{ for all } x, y \in \mathbb{R}_{(3)}$

- 8. $d(yx^2) = d(y)\sigma(x^2) + \tau(y)g(x)\sigma(x) + \tau(y)\tau(x)g(x)$, for all $x, y \in R$ (4)
- 9. From (2) and (4), we obtain:

 $\tau(\mathbf{y})(\tau(\mathbf{x})\mathbf{d}(\mathbf{x})-\tau(\mathbf{x})\mathbf{g}(\mathbf{x}))=0, \text{ for all } \mathbf{x},\mathbf{y} \in \mathbf{R}$ (5) Replacing y by yr in (5), to get: $\tau(vr)(\tau(x)d(x)-\tau(x)g(x))=0, \text{ for all } x, y, r \in \mathbb{R}$ (6) Again, left multiplying of (5) by $\tau(r)$, to get: $\tau(\mathbf{r})\tau(\mathbf{y})(\tau(\mathbf{x})\mathbf{d}(\mathbf{x})-\tau(\mathbf{x})\mathbf{g}(\mathbf{x}))=0, \text{ for all } \mathbf{x}, \mathbf{y}, \mathbf{r} \in \mathbf{R}$ (7) Subtracting (7) from (6), we get: $[\tau(\mathbf{y}),\tau(\mathbf{r})](\tau(\mathbf{x})\mathbf{d}(\mathbf{x}),\tau(\mathbf{x})\mathbf{g}(\mathbf{x}))=0, \text{ for all } \mathbf{x},\mathbf{y},\mathbf{r}\in\mathbf{R}$ (8) Since R has a commutator left nonzero divisor, we get: $\tau(x)d(x)=\tau(x)g(x)$, for all $x \in \mathbb{R}$ (9) Linearizing (9), we get: $\tau(x)d(y) + \tau(y)d(x) = \tau(x)g(y) + \tau(y)g(x), \text{ for all } x, y \in \mathbb{R}$ (10) That is: $\tau(x)(d-g)(y) + \tau(y)(d-g)(x) = 0$, for all $x, y \in \mathbb{R}$ (11) Replacing y by ry in (11), to get: $\tau(x)(d-g)(ry) + \tau(ry)(d-g)(x)=0$, for all x,y,r $\in \mathbb{R}$ (12) Again, left multiplying of (11) by $\tau(r)$, to get: $\tau(r)\tau(x)(d-g)(v) + \tau(r)\tau(v)(d-g)(x)=0$, for all x, v, r $\in \mathbb{R}$ (13) Subtracting (12) from (13), we get: $\tau(rx) (d-g)(y) - \tau(x)(d-g)(ry) = 0$, for all x,y,r $\in \mathbb{R}$ (14) Replacing x by sx in (14), to get: $\tau(rsx)(d-g)(y) - \tau(sx)(d-g)(ry) = 0, \text{ for all } x, y, r, s \in \mathbb{R}$ (15) Also, left multiplying of (14) by $\tau(s)$, to get: $\tau(\operatorname{srx})(d-g)(y) - \tau(\operatorname{sx})(d-g)(ry) = 0, \text{ for all } x, y, r, s \in \mathbb{R}$ (16) Subtracting (16) from (15), we get: $[\tau(r), \tau(s)] \tau(x)(d-g)(y)=0$, for all x, y, r, s $\in \mathbb{R}$ (17) Since R has a commutator left nonzero divisor, we get: $\tau(x)(d-g)(y)=0$, for all $x, y \in \mathbb{R}$ (18) That is: $\tau(x)d(y) = \tau(x)g(y), \text{ for all } x, y \in \mathbb{R}$ (19) Hence d and g are (σ, τ) -derivations.

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الأشتقاقات المزدوجة القوية-(σ,τ) على الحلقات

اكرام احمد سعيد الجامعة التكنولوجية استلم البحث في : 30 تشرين الثاني 2010 قبل البحث في : 27 شباط 2011

الخلاصة

لتكن R حلقة تجميعية. في هذا البحث قدمنا تعريف الأشتقاق المزدوج القوي-(σ,τ) واشتقاق جوردان المزدوج القوي-(σ,τ) في الحلقة R، ودراسة العلاقة بينهم. كذلك، ندرس الحلقات الأولية، الحلقات شبه الأولية، والحلقات التي لها مبدل قاسم غير صفري أيسر مع الأشتقاق المزدوج القوي-(σ,τ) للحصول على الأشتقاق -(σ,τ). أي ان R →R هما دالتين على الحلقة R.

الكلمات المفتاحية:

حلقة اولية، حلقة شبه اولية، مشتقة -(٥,٦)، الأشتقاق المزدوج القوي -(٥,٦)، اشتقاق جوردان المزدوج القوي -(٥,٦).